



3<sup>rd</sup> Vol MURI Review 2014



# Value-centered Information Theory for Adaptive Learning, Inference, Tracking, and Exploitation

[<http://wiki.eecs.umich.edu/voimuri>]

ARO W911NF-11-1-0391

Program manager: Liyi Dai

**Investigators:** Al Hero (PI), Raj Nadakuditi, John Fisher, Jon How, Alan Willsky, Randy Moses, Emre Ertin, Angela Yu, Michael Jordan, Stefano Soatto, Doug Cochran





# 3<sup>rd</sup> Year Vol MURI Review: Agenda

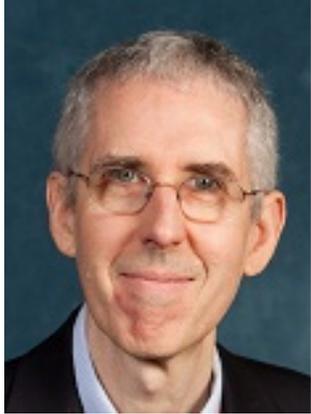


<b>Time</b>	<b>Activity</b>
8:00 -8:30	Get settled with coffee
8:30 -8:35	Welcome (Liyi Dai)
8:35 -8:50	Project overview (Al Hero)
8:50 -9:30	Mathematical foundations of Vol (Al Hero and Doug Cochran)
9:30 -10:10	Learning with information constraints (Michael Jordan)
10:10 -10:30	Break
10:30 -11:30	Poster highlight talks
11:30 -1:30	Poster session and lunch
1:30 -2:10	Information fusion and exploration (Stefano Soatto)
2:10 -2:50	Information planning (John Fisher and Jon How)
2:50 -3:10	Break
3:10 -3:30	Radar testbed (Emre Ertin)
3:30 -3:45	Wrapup (Al Hero)
3:45 -4:30	Government discussion and de-briefing
4:30	Adjourn





# MURI coPIs



Al Hero  
Michigan



Raj Nadakuditi  
Michigan



Randy Moses  
Ohio State



Emre Ertin  
Ohio State



Jon How  
MIT



John Fisher  
MIT



Alan Willsky  
MIT



Angela Yu  
UCSD



Stefano Soatto  
UCLA

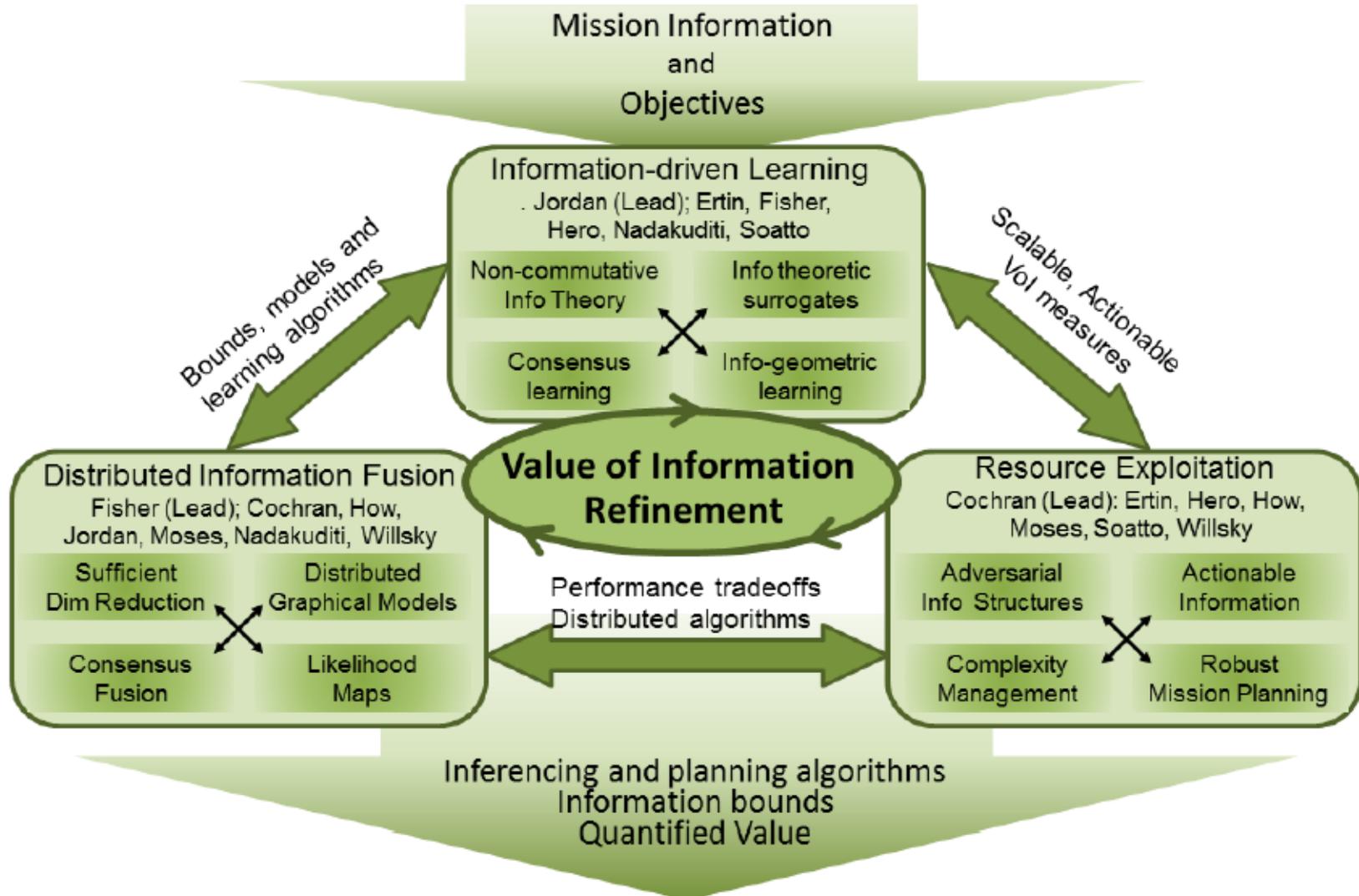


Mike Jordan  
UC Berkeley



Doug Cochran  
Arizona State







# Our MURI's principal aim



- To derive a comprehensive set of principles for task-specific information extraction, distributed information fusion, and information exploitation that can be used to design the next generation of autonomous and adaptive sensing systems.
- **Specific objectives:**
  - Develop analytical frameworks for quantifying value of information.
  - Study fundamental tradeoffs for information collection and fusion
  - Develop info processing algorithms with performance guarantees
  - Validate theory and algorithms on sensing testbeds at MIT, OSU, UCSD and UCLA
- **Technical approach:** value-centered information theory, machine learning and control.





# Design space is high dimensional



## Information sources

- Collected sensor data
- Target/clutter signatures
- Contextual information
- Soft data

## Decision tasks

- Detect target
- Estimate target location
- Identify target class
- Assess threat level

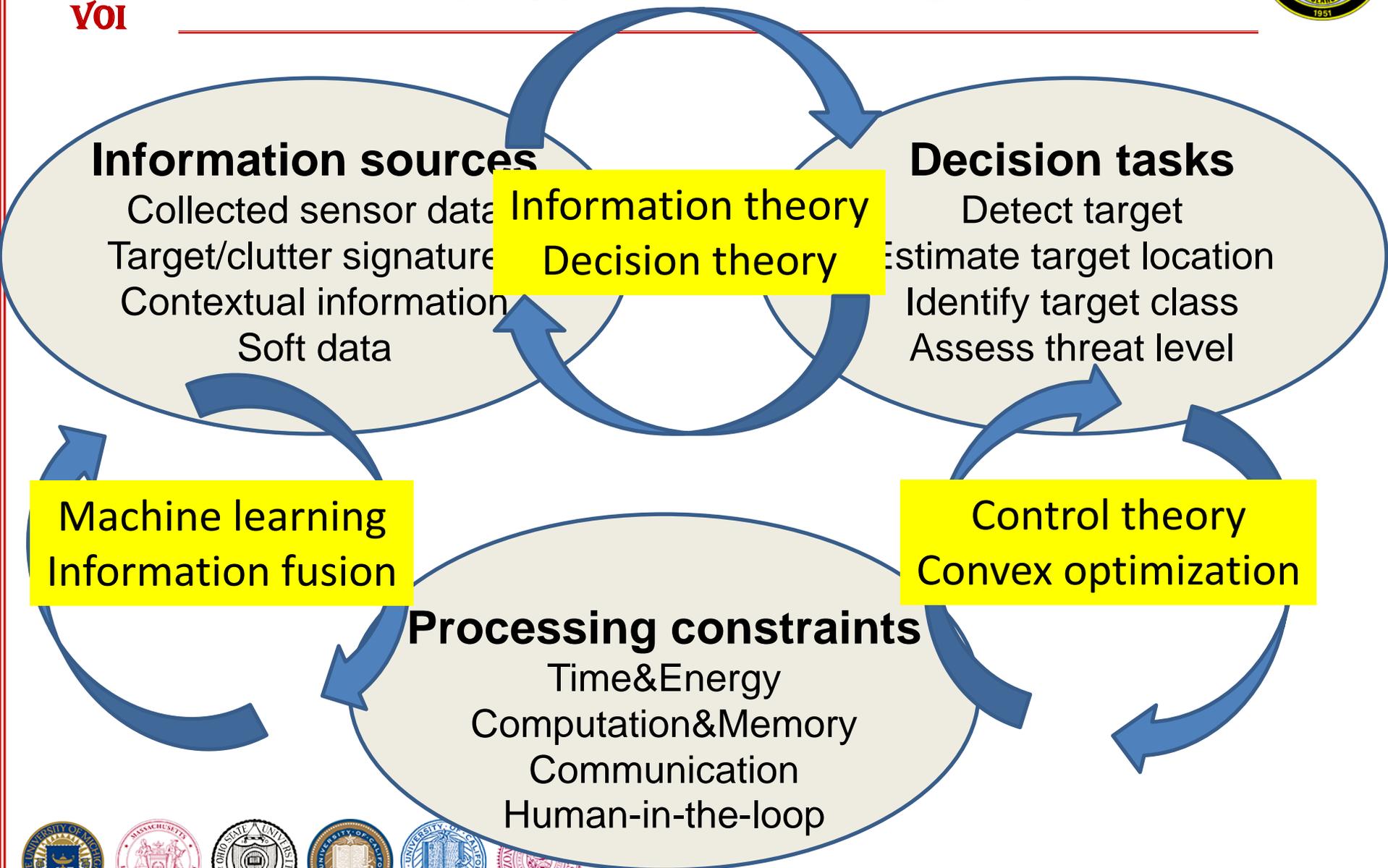
## Processing constraints

- Time&Energy
- Computation&Memory
- Communication
- Human-in-the-loop





# Theory applicable to design space





# Theory applicable to design space



## Central questions addressed by our MURI

- What is intrinsic value of information for a task?
- How do constraints affect value?
- What algorithms ensure max value?
- How to overcome computational bottlenecks?

## Our technical approach to address questions

- Value-centered information theory
- Information-driven data fusion
- Information-aware controlled sensing/processing

Communication





# Research highlights



- Information-driven structure learning and representation
  - Learning in graphical models latent variable structures [Hero, How, Fisher]
  - Trade-offs between complexity and performance [Ertin, Fisher, Hero, Jordan]
  - Representations of information for video analysis [Hero, Soatto]
- Distributed information fusion
  - Decentralized learning and local information aggregation [Ertin, Hero, Jordan, Moses]
  - Subspace processing and fusion of information [Ertin, Jordan, Nadakuditi]
  - Robust information-driven fusion [Ertin, Fisher, Hero]
  - Multimodality fusion with missing or unreliable information [Hero]
- Active information exploitation for resource management
  - Vol proxies for resource management [Ertin, Hero, Cochran]
  - Information geometric foundations [Cochran, Hero]
  - Models of human and human-machine interaction [Hero, Yu]
  - Mission adaptive planning with convex proxies [Hero, How]





# Research highlights (ctd)



- Application domains being considered
  - Space-time adaptive processing (STAP) (Ertin, Cochran, Hero, Zelnio)
  - Moving target estimation in SAR (Hero, Zelnio)
  - Robust video motion segmentation (Nadakuditi, Hero)
  - Object and feature recognition in video (Soatto)
  - Fusion of WAMI and LIDAR imagery (Fisher)
  - Intruder detection with multi-modality sensors (Hero, Nasrabadi)
  - Human collaboration and HMI modeling (Yu, Hero, Sadler)
  - Wide area search and mission adaptive planning (How, Hero)
  - Social media, crowdsourcing and text streams (Hero and Jordan, Kaplan)
- Experimental model building and validation
  - Factors influencing human performance in collaborative tasks (Yu)
  - Radar test-bed to validate Vol proxies and associated algorithms (Ertin)





# 2013 review government comment 3



- **The committee noted current efforts addressing relevant subproblems of Value of Information (VoI). Team needs to coordinate research activities toward establishing a rigorous, foundational framework of value of information for distributed fusion. A unifying theme is needed...**  
Research coordination has occurred on several levels and several subgroups have been working together on foundational themes. This will be reported today in the talks and posters





# Previous government comments 5



- **...the highest priority of research be to establish a framework first using whatever type of data the team is familiar with.** This has been and continues to be the team's approach to model validation in building our framework for Vol.
- **Generalization of the framework to include soft data could be done later with possible modifications. The team is certainly encouraged to include soft data in research.** We are developing general theory capable of handling hard and soft data. Several coPIs will report on soft data in the talks and posters.





# Previous government comment 6



- **UCSD is new to the team and offers complementary research agenda. The focus of research should be on human aspects of value of information, going beyond attention detection and eye tracking.**

We report results on modeling human behavior in problem solving experiments. As shown in Angela Yu's ARL presentation last June, UCSD's results generate models for the team's efforts on human-in-the-loop and collaborative learning.





# Previous government comment 7



- **While the government committee understands the tradeoff between complexity and elegance of a theory, it is desirable for research efforts to focus on theory and methods that are applicable to problems of practical complexity as opposed to results that are valid only under overly simplified assumptions.**

Our team recognizes the importance of model validation and applying our results to real world data. The team has achieved this through designing experiments, disciplinary collaborations, and technology transitions.





# Previous government comment 8



- **Future research is encouraged to place more emphasis on multimodality sensors, particularly visual modality.**
- This year we report on several multimodality sensing problems, including those involving visual data.





# Previous government comment 10



- **The government committee discussed the use of real data for research validation and motivation....**  
Real data from various sources, including ARL, AFRL, and co-PI labs, is being used to validate models and results. We expect to coordinate with ARDEC to explore other multimodal data sources.
- **The team will set up a testbed, under the support of a DURIP grant, to address the need of creating realistic scenarios for research validation, verification, and problem motivation.**  
We anticipate collection of radar data from the DURIP testbed to begin by the end of the calendar year.





# Today's posters



1. Gene T. Whipps, Emre Ertin, Randolph L. Moses, "A consensus based decentralized EM for a mixture of factor analyzers"
2. Diyan Teng and Emre Ertin, "Learning to Aggregate Information for Sequential Inferences"
3. Nithin Sugavanam, Emre Ertin, "Optimal measurement matrix design for structured signals in clutter and noise"
4. K. Greenewald, A.O. Hero, "Regularized Block Toeplitz Covariance Matrix Estimation via Kronecker Product Expansions"
5. H.W. Chung, T. Tsiligkaridis, B. Sadler, A. Hero, "Collaborative 20 questions"
6. Z. Meng, B. Erikson, A.O. Hero, "Learning Latent Variable Gaussian Graphical Models"
7. Zhang, Chen, Zhou and Jordan: Spectral methods meet EM: A provably optimal algorithm for crowdsourcing
8. Zhang, Wainwright and Jordan: Lower bounds on the performance of polynomial-time algorithms
9. Nishihara, Jegelka and Jordan: On the convergence rate of decomposable submodular function minimization
10. J. Duchi, M. Jordan, M. Wainwright and Wibisono: Optimal rates for zero-order optimization: the power of two function evaluations
11. Brian E. Moore, Raj Rao Nadakuditi, and Jeffrey A. Fessler, "Improved robust PCA using low-rank denoising with optimal singular value shrinkage"
12. L. Crider and D. Cochran, "Value of Information Sharing in Network Signal Detection"
13. S. Zhang, A. Tran and A. Yu, "Personality and Behavioral Predictors of Human Exploration/Exploitation Behavior in a Bandit Task"
14. B. Mu and J. How, "Focused information gathering with an application in SLAM"
15. Josh Hernandez, Konstantine Tsotsos, Gottfried Graber, and Stefano Soatto, "Scene Segmentation with Dense Reconstruction from Monocular Video"
16. Konstantine Tsotsos and Stefano Soatto, "Robust Visual-Inertial Navigation and Mapping"

