

Signal-plus-noise-plus-outliers model

$$\tilde{X} = L + S + X$$

- ▶ $\tilde{X} = n \times m$ signal-plus-noise-plus-outliers matrix
- ▶ $L =$ low-rank signal matrix

$$L = \sum_{i=1}^r \theta_i u_i v_i^H$$

- ▶ S is a sparse matrix of *outliers* modeled as

$$S_{ij} = \begin{cases} q_{ij} & \text{with probability } p \\ 0 & \text{with probability } 1 - p, \end{cases}$$

- ▶ q_{ij} drawn from *unknown* distribution $q(s)$ with

$$\mathbb{E}[q] = 0 \quad \mathbb{E}[q]^2 = \sigma_q^2 \quad \mathbb{E}[q]^4 < \infty,$$

- ▶ $X =$ noise-only matrix having i.i.d. elements with

$$\mathbb{E}[X_{ij}] = 0 \quad \mathbb{E}[X_{ij}^2] = \sigma^2/m \quad \mathbb{E}[X_{ij}^4] < \infty$$

Problem Statement

- ▶ Objective: Given \tilde{X} , estimate L as accurately as possible
- ▶ Applications:
 - Foreground/background separation
 - Dynamic MR imaging

Need for Robust PCA

- ▶ Assume L is *incoherent* with Euclidean basis. Let

$$\tilde{X} = \sum_i \tilde{\sigma}_i \tilde{u}_i \tilde{v}_i^H,$$

Theorem: As $n/m_n \rightarrow c \in (0, \infty)$,

$$|\langle u_i, \tilde{u}_i \rangle|^2 \xrightarrow{\text{a.s.}} \begin{cases} 1 - \frac{c(1 + \bar{\theta}_i^2)}{\bar{\theta}_i^2(\bar{\theta}_i^2 + c)} & \text{if } \bar{\theta}_i > c^{1/4} \\ 0 & \text{otherwise,} \end{cases}$$

and

$$|\langle v_i, \tilde{v}_i \rangle|^2 \xrightarrow{\text{a.s.}} \begin{cases} 1 - \frac{(c + \bar{\theta}_i^2)}{\bar{\theta}_i^2(\bar{\theta}_i^2 + 1)} & \text{if } \bar{\theta}_i > c^{1/4} \\ 0 & \text{otherwise,} \end{cases}$$

where

$$\bar{\theta}_i = \lim_{m \rightarrow \infty} \frac{\theta_i}{\sqrt{pm\sigma_q^2 + \sigma^2}}$$

- ▶ Insight:
 - If $\sigma_q^2 = O(1)$ and $pm \rightarrow \infty$, then $\bar{\theta}_i \rightarrow 0$
 - $\Rightarrow p \geq O(\log m/m)$ will “break” PCA

Nuclear-norm based Robust PCA

- ▶ Solves the optimization problem

$$\{\hat{L}_{\text{svt}}, \hat{S}_{\text{svt}}\} = \arg \min_{L, S} \frac{1}{2} \|\tilde{X} - (L + S)\|_F^2 + \lambda_L \|L\|_* + \lambda_S \|S\|_1,$$

via alternating minimization

$$\begin{aligned} L_{k,\text{svt}} &= \mathbf{SVT}_{\tau_k \lambda_L}(M_{k-1,\text{svt}} - S_{k-1,\text{svt}}) \\ S_{k,\text{svt}} &= \mathbf{soft}_{\tau_k \lambda_S}(M_{k-1,\text{svt}} - L_{k-1,\text{svt}}) \\ M_{k,\text{svt}} &= L_{k,\text{svt}} + S_{k,\text{svt}} - \tau_k(L_{k,\text{svt}} + S_{k,\text{svt}} - \tilde{X}), \end{aligned}$$

where $\mathbf{SVT}(\cdot)$ is the *singular value thresholding* operator

$$\mathbf{SVT}_\lambda(Y) = \sum_{i=1}^n (\sigma_i - \lambda)_+ u_i v_i^H$$

- ▶ Disadvantages:

- How to select parameters λ_L , λ_S , and τ_k ?
- Provably suboptimal low-rank matrix recovery

OptShrink: Low-rank recovery by optimal shrinkage

- ▶ Consider the oracle low-rank denoising problem

$$\mathbf{w}^{\text{opt}} = \underset{[w_1, \dots, w_r]^T \in \mathbb{R}^r}{\operatorname{argmin}} \|L - \sum_{i=1}^r w_i \tilde{u}_i \tilde{v}_i^T\|_F^2$$

- ▶ Under Theorem hypotheses and when $S = 0$, we have

$$w_i^{\text{opt}} = \Re_+ \left\{ \sum_{j=1}^r \theta_j (\tilde{u}_j^H u_j) \cdot (v_j^H \tilde{v}_i) \right\} \xrightarrow{\text{a.s.}} -2 \frac{D_{\mu_X}(\tilde{\sigma}_i)}{D'_{\mu_X}(\tilde{\sigma}_i)},$$

where $q = \min(m, n)$, and

$$D_{\mu_X}(z) = \left[\frac{1}{q-r} \sum_{i=r+1}^q \frac{z}{z^2 - \tilde{\sigma}_i^2} \right] \times \left[\frac{1-c}{z} + \frac{c}{q-r} \sum_{i=r+1}^q \frac{z}{z^2 - \tilde{\sigma}_i^2} \right]$$

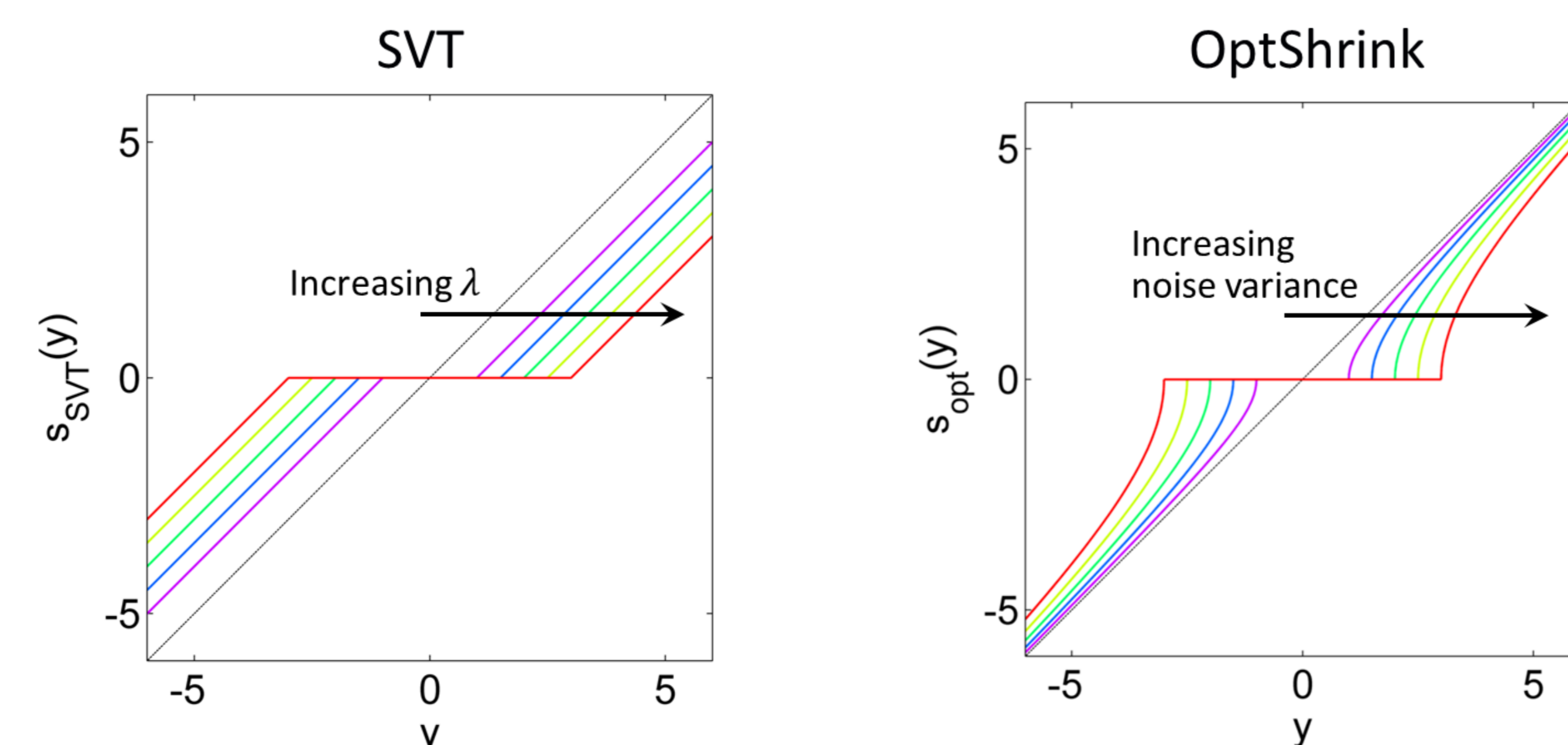
- ▶ D-transform:

- Matrix analogue of log-Fourier transform

- ▶ Insights:

- Optimal shrinkage is *inversely related* to *eigen-SNR*

Why is OptShrink better than ℓ_1 type shrinkage?



Proposed Approach

- ▶ Replace SVT with OptShrink:

$$\begin{aligned} L_k &= \mathbf{OptShrink}_r(M_{k-1} - S_{k-1}) \\ S_k &= \mathbf{soft}_{\tau_k \lambda_S}(M_{k-1} - L_{k-1}) \\ M_k &= L_k + S_k - \tau_k(L_k + S_k - \tilde{X}), \end{aligned}$$

where

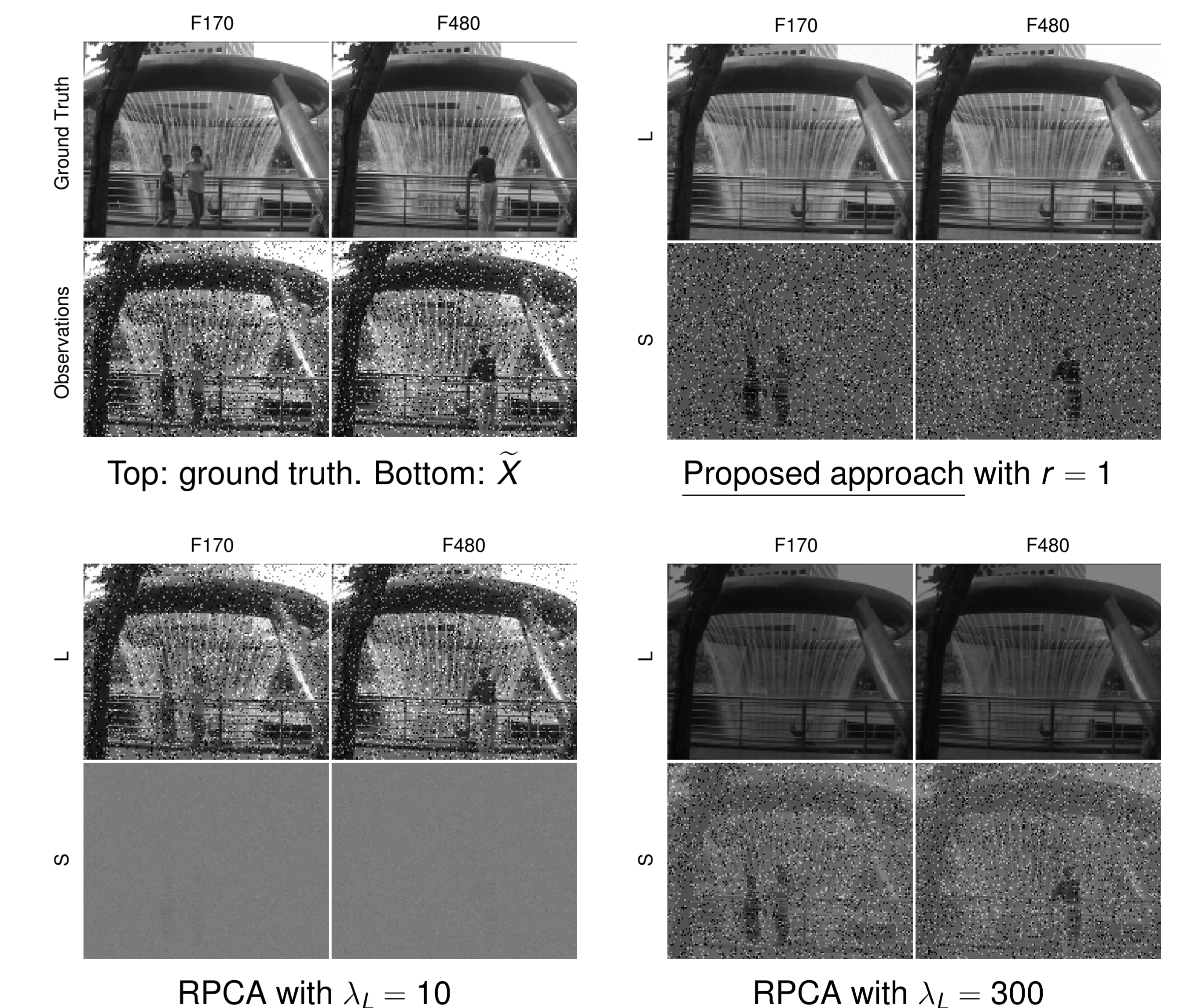
$$\mathbf{OptShrink}_r(Y) = \sum_{i=1}^r \left(-2 \frac{D_{\mu_Y}(\sigma_i)}{D'_{\mu_Y}(\sigma_i)} \right) u_i v_i^H$$

- ▶ Advantages:

- *Explicit* rank regularization (cf. implicit SVT)
- OptShrink is optimal low-rank denoiser
- Small λ_L does not denoise
- Large λ_L shrinks strong subspaces and leaves artifact

Results: Background subtraction task

- ▶ Random saturations as outliers



References

- ▶ R. R. Nadakuditi, “OptShrink: An algorithm for improved low-rank signal matrix denoising by optimal, data-driven singular value shrinkage,” *IEEE Trans. of IT*, May 2014.
- ▶ B. Moore, R. R. Nadakuditi, and J. Fessler, “Dynamic MRI reconstruction using low-rank plus sparse model with optimal rank regularized eigen-shrinkage,” *ISMRM*, May 2014.
- ▶ R. Otazo, E. J. Candès, and D. K. Sodickson, “Low-rank and sparse matrix decomposition for accelerated dynamic MRI with separation of background and dynamic components,” *Magn. Reson. Med.*, 2014.